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Dealing with Uncertainty in Spatially Explicit Population Models

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Abstract

It has been argued that spatially explicit population models (SEPMs) cannot provide reliable guidance for conservation biology because of the difficulty of obtaining direct estimates for their demographic and dispersal parameters and because of error propagation. We argue that appropriate model calibration procedures can access additional sources of information, compensating the lack of direct parameter estimates. Our objective is to show how model calibration using population-level data can facilitate the construction of SEPMs that produce reliable predictions for conservation even when direct parameter estimates are inadequate. We constructed a spatially explicit and individual based population model for the dynamics of brown bears (*Ursus arctos*) after a reintroduction program in Austria. To calibrate the model we developed a procedure that compared the simulated population dynamics with distinct features of the known population dynamics (= patterns). This procedure detected model parameterizations that did not reproduce the known dynamics. Global sensitivity analysis of the uncalibrated model revealed high uncertainty in most model predictions due to large parameter uncertainties (coefficients of variation $CV \approx 0.8$). However, the calibrated model yielded predictions with considerably reduced uncertainty ($CV \approx 0.2$). A pattern or a combination of various patterns that embed information on the entire model dynamics can reduce the uncertainty in model predictions, and the application of different patterns with high information content yields the same model predictions. In contrast, a pattern that does not embed information on the entire population dynamics (e.g., bear observations taken from sub-areas of the study area), does not reduce uncertainty in model predictions. Because population-level data for defining (multiple) patterns are often available our approach could be applied widely.

Keywords: *Ursus arctos*; individual-based model; model calibration; pattern-oriented modeling; population dynamics; spatially explicit population model; uncertainty

Introduction

Over the last two decades the importance of spatial processes in population dynamics has been increasingly recognized, and the way that population dynamics are impacted by landscape structure has become a major subject of research and debate in ecology and conservation biology (e.g., see reviews of Dunning *et al.*, 1992; Wiens *et al.*, 1993; Fahrig and Merriam, 1994). Habitat heterogeneity is believed to affect most aspects of the biology of a population and several theoretical constructs have been proposed for characterizing the impact of landscape structure on population dynamics (e.g., Fahrig and Merriam, 1994). Clearly, the spatial structure of the landscape in which species are found must be explicitly considered when landscape composition and physiognomy play a role in determining population dynamics (Wiegand *et al.*, 1999). For example, in many cases the quality and distribution of habitat is important for assessing viability of endangered species, for planning reintroduction programs (e.g., Schadt *et al.*, 2002), or for managing expansion of large carnivores into new areas (e.g., Mladenoff *et al.*, 1999). Spatially explicit population models (SEPMs) can provide a powerful tool for analyzing the impact of spatial processes and landscape structure on (meta)population dynamics (e.g., Dunning *et al.*, 1995; Pulliam and Dunning, 1995; Wiegand *et al.*, 1999, *this issue*). These models often use a geographical information system (GIS) database to compile maps on habitat quality, and apply a population model that relates demographics of the species explicitly to the landscape in which the organism lives. Individual-based models allow for the inclusion of behavioral rules describing the response of individuals to the landscape and can link the individual's use of space (dispersal and habitat selection) directly to population and metapopulation phenomena (Lima and Zollner, 1996; Wiegand *et al.*, 1999). Consequently, spatially explicit population models have been increasingly used in conservation as awareness of landscape processes has expanded and tools for analyzing landscape-scale phenomena have developed (Beissinger and Westphal, 1998).

Criticism of spatially-explicit population models

The initial enthusiasm about spatially-explicit population models (Pulliam and Dunning, 1995), however, has been dampened by critical voices (e.g., Doak and Mills, 1994, Ruckelshaus *et al.*, 1997, Beissinger and Westphal, 1998, Hartway *et al.*, 1998) outlining the data requirements, problems associated with parameter estimation, and possible magnifications of parameter errors which may make the development of such models an onerous process (Kareiva *et al.*, 1997; Beissinger and Westphal, 1998). Most of the criticism of spatially-explicit population models is based on a series of articles (Wennergren *et al.*, 1995; Ruckelshaus *et al.*, 1997; Meir and Kareiva, 1997; Hartway *et al.*, 1998) in which the

authors examined a simple spatially explicit model for organisms dispersing in a fragmented landscape. For example, the “grim message” emerging from the analysis of Wennergren *et al.* (1995) was that “however appealing may be spatially explicit models of individual behavior, they are likely to be highly unreliable given our uncertainties about dispersal behavior and rates.” This claim was later justified by the publication of the details of the model in Ruckelshaus *et al.* (1997). They found that errors due to uncertainty in a parameter describing per step mortality propagated into larger errors in predicted dispersal success. Although this key result turned out to be based on an erroneous analysis of the model (Mooij and DeAngelis, 1999; Ruckelshaus *et al.*, 1999) it captured well the spirit of general pessimism on the future of spatially explicit population models. In fact, SEPMs seemed to be at a dead end. It was argued, that even under the best circumstances, spatially explicit models may not be able to predict, with a reasonable certainty, the number of individuals in a landscape (Dunning *et al.*, 1995; Beissinger and Westphal, 1998).

Pattern-oriented modeling and model uncertainty

Clearly, for many applications in ecology and conservation biology there never will be enough data to produce accurate, direct field estimates of parameters related to demographics and dispersal. This is not because of insufficient data collection or data analysis techniques, but because of low individual numbers and the resulting high inherent stochasticity (Doak and Mills, 1994, Beissinger and Westphal, 1998). Also, it is true that no amount of clever modeling or detailed GIS habitat maps can circumvent the need of SEPMs for estimates of demographic and dispersal parameters (Ruckelshaus *et al.*, 1999).

The point we want to make in this contribution is that parameters need not necessarily be estimated directly by field observations. Astute modeling can help to access other sources of data (e.g., population-level data such as time series) which can be used for indirect parameter estimation (Wiegand *et al.*, 1998). Only recently, pattern-oriented modeling (Grimm, 1994; Grimm *et al.*, 1996; Wiegand *et al.*, in press) has been proposed as framework for exploiting the available data at *all* steps of the modeling process: from the initial model construction to parameter estimation and to detection of deficiencies in the model structure and knowledge. The pattern-oriented modeling strategy relies on additional data contained in observed patterns which arise as high level output of population dynamics as a consequence of the interaction of all processes of population dynamics and constraining factors such as management actions (e.g., release of individuals, or hunting), or landscape structure. In conservation biology, such patterns comprise, for example, presence-absence data in patchy populations (e.g., Hanski, 1994), or time-series of the size of a fraction of the population [e.g., the number of females with cubs in Wiegand *et al.* (1998); Wiegand *et al.* (*this issue*)]. These patterns are a rich source of data which is usually not used in population models because it

cannot be directly translated into estimates of model parameters or included into the rule set of a population model. The data of such patterns, however, may help us to determine a correct model structure and parameter values indirectly, and is the key for addressing problems associated with uncertainty.

To reveal the “hidden” data it is important to have a “structurally realistic” model that (1) matches the predominant scales of the real system to facilitate a direct comparison of model relations with observations, and which (2) contains a “correct” representation of the basic processes and interactions that determine the dynamics of the system on the given scales (DeAngelis and Mooij, in press). A systematic comparison of the observed pattern with patterns produced by different modifications of the model will detect implausible model parameterizations (e.g., Wiegand *et al.*, 1998) or model structures (e.g., Jeltsch *et al.*, 1999) and thus allows for adjustment of uncertain or unknown parameters or processes, avoiding error propagation. In structurally realistic models one can compare model predictions and internal model relations with empirical data, which adds further possibilities for evaluating model performance. Validation and exhaustive sensitivity analyses of spatially explicit population models, however, has been rarely undertaken (but see Higgins *et al.*, 2000; McCarthy *et al.*, 2000; Rushton *et al.*, 2000), mainly because of the computational effort involved, and because results can be difficult to interpret.

In this article we used the expansion of brown bears (*Ursus arctos*) into the eastern Alps (Wiegand *et al.*, *this issue*) as an example for dealing with uncertainty in spatially explicit population models. We show how one can obtain a credible spatially-explicit population model without access to direct field estimates of most model parameters. We constructed a structurally realistic model that includes data on demographic processes, social structure, and dispersal behavior of brown bears. The model synthesizes knowledge that has been accumulated over many years of research on brown bear populations (e.g., summarized in Swenson *et al.*, 2000). The specific aim of this model was to investigate population dynamics of brown bears in Austria after a reintroduction program, and to indirectly assess current key variables of population dynamics, such as population sizes and growth rates, dispersal distances, or mortality rates within different population nuclei (see Wiegand *et al.* *this issue*). Here we perform an extensive sensitivity analysis of the model and evaluate different population-level data sets (= patterns) in their ability to constrain model predictions. We show that a pattern (or a combination of several patterns) that embeds data on the entire population dynamics (a genuine pattern sensu Grimm *et al.*, 1996) can reduce the uncertainty in model predictions substantially, and that model calibration with different genuine patterns yield consistent model predictions.

INSERT FIGURE 1

Methods

SPECIES AND POPULATION: BROWN BEARS IN THE EASTERN ALPS

After the extirpation of the last resident bear in southern Austria in 1884 (Rauer and Gutleb, 1997), migrants from Slovenia reached Austria and Italy only sporadically. During 1989–1993 WWF Austria released three bears from Slovenia and Croatia (Rauer and Gutleb, 1997), and in 1991 Slovenia banned the killing of bears outside of a core management area. This was of particular importance for bear recovery in Austria because bears might now disperse unhindered from the large source population in southern Slovenia to Austria. Since then the subpopulation in central Austria has grown (Fig. 1) and nine litters with a total of 23 cubs were observed between 1991 and 2000 (Rauer *et al.*, 2001). Population estimates are about 25–30 bears in Austria (Zedrosser *et al.*, 1999; Swenson *et al.*, 2000).

MODEL DEVELOPMENT

The individual-based spatially explicit model and its development are fully described in Wiegand *et al.* (*this issue*), here we provide only a brief description.

Selection of scales. — To model the size of a bear's home range we selected a 10 km × 10 km raster-grid as spatial resolution of our model. This grain is slightly finer than the typical scale of an individual's home range, which can cover several hundred square kilometers in Austria (Rauer and Gutleb, 1997; Kaczensky and Knauer, 2000). We defined a square of nine cells ($\approx 900 \text{ km}^2$) as the maximum size of a female's home range, and a square of 36 cells ($\approx 3600 \text{ km}^2$) as the maximum size of a male's home range. Because males generally occupy home ranges several times larger than those of females and disperse considerably larger distances, we join a square of four cells to one “virtual” cell and apply all the rules for male dispersal and establishment of home ranges on this double scale.

The habitat model. — An important ingredient that constrains the spatial dynamics of the bear population is the habitat model that designates each 10 km × 10 km raster cell an index value Z of habitat quality, which ranged from $Z = 0$ (completely unsuitable) to $Z = 9$ (highest suitability). The map of habitat quality defined the landscape in which individuals were allowed to disperse, settle, reproduce, and die. The original habitat model was developed with data from 1947 radiolocations of 23 bears that were trapped between 1993 and 1998 in Slovenia (Kaczensky *et al.*, 2000) and applied to the area of the whole eastern Alps (Fig. 3 in Wiegand *et al.*, *this issue*). Validation of the habitat model with an independent data set of five bears in central Austria (Rauer and Gutleb, 1997) and an additional validation in Wiegand *et al.* (*this issue*) using all bear observations in Austria showed that the best areas in the habitat model are indeed areas where bears were observed.

Demographic model. — The demographic model determined the fates of individuals throughout life and simulated the life-history events of birth, independence, and death, as well as dispersal of young individuals and reproduction for adults. Each of these demographic events was determined stochastically. Mortality was modified as a function of home range size, and only females occupying a home range could reproduce. We did not consider temporal environmental variation because it is low for the long-lived brown bears (Sæther *et al.*, 1998; Wiegand *et al.*, 1998), and because we focused more on spatial than demographic aspects.

Spatial submodel. — We modeled only the dispersal movement of non-resident bears; movement of residents and dependent cubs within their home ranges was neglected. To include a process that describes spacing of home ranges and attraction of dispersing males by females in a simple but reasonable way, we introduced a variable termed habitat attractiveness that describes the attraction of a given $10 \text{ km} \times 10 \text{ km}$ cell for dispersing males and females. For empty cells, the attractiveness was given through the index of habitat suitability Z , but for females it was reduced when the cell was already within the home range of other individuals. For males the attractiveness is increased when more than one female occupied the cell (for details see Wiegand *et al.*, *this issue*).

After independence, non-resident bears dispersed and searched for their own home range. They were allowed every year to perform S_{\max} site-sampling steps and moved one grid cell per step, selecting a neighboring cell at random with a probability directly proportional to the attractiveness of the cell, relative to that of the other neighboring cells. We assumed a per step mortality rate m_s during dispersal. Movement stopped when the individual found an acceptable home range. A potential home-range was acceptable if the sum of the attractiveness of a selection of cells taken from the nine cells, comprising the actual location of the individual and its eight neighboring cells, exceeded a threshold A_{\min} . Surviving individuals that did not find a home range continued to disperse in the next year.

Because individuals with larger home ranges had to move more compared to individuals with smaller home ranges, we assumed that the age-dependent risk of mortality declined for resident individuals with a factor $(c_m + [1 - c_m][s/9])$ if the size s of their home range was smaller than nine cells. The parameter c_m defined the degree of reduction of mortality due to smaller home ranges. For non-resident independent bears mortality was the same as for residents with maximal home range size (i.e., $s = 9$).

Bear management. — The bear releases and the data on the fate of the two released females are important constraining factors in central Austria. Since we know exactly what happened to these bears, we included them in the model deterministically. In the model we released bears of the same age and sex as those in the wild, in the same area (1989 a three year old female, 1991 a six year old pregnant female, and 1993 a 4-year-old male), and we

included the three litters and the subsequent death of the two released females deterministically.

One management parameter that influences immigration into Austria and Italy is the annual probability J of bears being hunted outside the core area in Slovenia. To model the management practice before 1992 we assumed hunting as an additional annual risk of mortality $J < 1$ independent of age or sex. In the case of protection outside the core area in Slovenia (the current management practice), we set $J = 0$.

The dynamics of bears in the core area in Slovenia was not within the scope of our model. We therefore included only the source function of the core area, which is important for our aim. To this end we placed each year at average s^F females and s^M males at random locations at the northern border of the core area (Fig. 1) and simulated their dispersal into northern Slovenia and Austria.

CONVENTIONAL DETERMINATION OF PARAMETER VALUES

Wiegand *et al.* (*this issue*) determined the values that are directly accessible from data from Austria and Slovenia (distribution of litter sizes, age of first reproduction, interbirth interval). For parameters on dispersal, and establishment of home ranges, these authors used the sparse data available from Austria and restricted the range of these parameters additionally with data on brown bears in Scandinavia and from other sources (e.g., Swenson *et al.*, 2000). For constraints of the values of the unknown mortality rates they used data from Scandinavia (Sæther *et al.*, 1998), northern Spain (Wiegand *et al.*, 1998), and data from Yellowstone National Park, Wyoming, USA (summarised in Wiegand *et al.*, 1998). Other unknown parameters, such as the number of immigrants from the core area in Slovenia into northern Slovenia, or the effect of home range size on mortality, were varied over a wide range. A complete listing of all model parameters and their ranges are given in Wiegand *et al.* (*this issue*: Table 1).

INSERT FIGURE 2

MODEL CALIBRATION USING POPULATION-LEVEL DATA

We used two data sets from field observations on brown bears in Austria, Slovenia, and Italy for model calibration. The first data set was a 10-yr time series from central Austria of females with cubs of the year (Fig. 2A), the second was the bear observation data set (Fig. 2B) which was collected during the bear monitoring program in Austria (Rauer and Gutleb, 1997, Rauer *et al.*, 2001).

We grouped the data on bear observations within a 10 km × 10 km cell into four coarse classes (0, 1–3, 4–10, > 10 observations, Fig. 2B). Although we cannot use the number of observations as a direct estimation of bear population size (e.g., Rauer and Gutleb, 1997; Swenson *et al.*, 1998), we assumed a higher density in cells with more observations. One problem with the number of observations is that more reports may come from areas that are just receiving their first immigrating bears because they are exciting and newsworthy. To improve this regional comparability, we did not compare observation data for the entire eastern Alps with simulated bear densities, but separately within the three subareas (central Austria, Carnic Alps, and Karawanken; Fig. 1). No females were observed in the transition area between central and southern Austria (Fig. 2B). We used this information as additional pattern that indicated that females of the two subpopulations in southern Slovenia and central Austria were not linked.

In summary, for comparison between simulated and observed data we investigated five different observed patterns derived from the two data sets: (1) the low female density in the transition area between central and southern Austria (Fig. 2B), (2–4) the observed bear density classes in central Austria, the Carnic Alps, and the Karawanken, respectively, (Fig. 4B), and (5) the time series of females with cubs (Fig. 2A).

INSERT TABLE 1

GLOBAL SENSITIVITY ANALYSIS AND MODEL PREDICTIONS

In Wiegand *et al.* (*this issue*) we analyzed only model parameterizations that satisfied the pattern of females with cubs (Fig. 2A), whereas here we aim to analyze the full behavior of the model by sampling the entire parameter space (i.e., a global sensitivity analysis). To this end we created model parameterizations by assigning random values for the 13 uncertain parameters, independently of each other, from uniform distributions within the ranges given in Table 1. The range of variation of each parameter reflects the degree of uncertainty in its estimate. For each model parameterization we performed as many replicate simulations as necessary to obtain 35 replicates in which the female population did not become extinct in central Austria. We neglected extinct replicates because females were present all years in central Austria. To investigate the sensitivity of the model output to the parameters, we calculated the mean values of eighteen model predictions from the output of the 35 non-extinct replicate simulations (Table 2). We then performed multiple linear regressions with each model prediction as the dependent variable and the 13 parameters as independent variables (McCarthy *et al.*, 1995). The resulting regression equation relates the parameters of the population model to predicted variables of population dynamics. Because we sampled the parameter space randomly multicollinearity did not occur.

We scaled the dependent and independent variables to values between 0 and 1 and used the resulting coefficients β_i of the linear regression as indices of the sensitivity of the model output to the parameters p_i . A coefficient $|\beta_i| = 1$ indicates strong sensitivity whereas parameters with small values $|\beta_i| \ll 1$ have little impact on the model prediction. To perform a rough sensitivity ranking of the model parameters p_i , we calculated the average of $|\beta_i|$ for all eighteen model predictions.

INSERT TABLE 2

IMPACT OF STOCHASTICITY ON MODEL PREDICTIONS

To obtain an estimate of the variation in the model predictions due to stochasticity, we repeated the procedure for determining model predictions 50 times with the same model parameterization. We assessed the impact of stochasticity on model predictions for six model parameterizations which were randomly chosen among the ten best. For each model parameterization we calculated the resulting mean (*mean*) and standard deviation (*sd*) of the 50 replicate estimations for each model prediction. We used the average of the coefficients of variation $CV = sd/mean$ of the six model parameterizations to reflect uncertainty due to stochasticity.

MODEL CALIBRATION: SYSTEMATIC COMPARISON BETWEEN OBSERVED AND SIMULATED PATTERNS

In this step patterns produced by the model are systematically compared with the patterns observed in the field. To assess whether or not simulated patterns match an observed pattern, we need to measure the deviation E between the patterns, and we need a criterion to define confidence intervals for accordance between the patterns. This criterion acts as a “filter” for implausible model parameterizations.

Measure to compare the pattern of females with cubs. — To measure the deviation between one simulated time series $S(t)$ of females with cubs at years $t = 1991$ –2000 with the corresponding data $[D(t)]$ we used the measure

$$E^{\text{cub}} = \sqrt{\frac{1}{10} \sum_{t=1991}^{2000} \left[\frac{D(t) + D(t-1)}{2} - \frac{S(t) + S(t-1)}{2} \right]^2} \quad (1),$$

which is basically the sum of squares of the 2-year running mean of the two time series [note that $S(1990) = 0$, $D(1990) = 0$], but for better interpretation we transformed it to be analogous to the standard deviation. We chose the 2-year running mean to capture the population trend because females in central Austria appear to have a 2-year interbirth interval. To compare the 35 replicate simulations for each model parameterization to the observed pattern, we use the average E_{35}^{cub} of the 35 resulting error indices E^{cub} .

We defined an acceptance threshold for E_{35}^{cub} using a randomization approach, and compared E_{35}^{cub} to a null model of random litters. For this purpose we created 35 random time series by distributing six litters between 1994 and 2000 at random and including the three litters of the two released females deterministically. For these 35 random time series we calculated the resulting average error index E_{35}^{random} analogously to the calculation of E_{35}^{cub} . We repeated this procedure 5000 times to obtain the distribution of E_{35}^{random} and use the criterion that E_{35}^{cub} should be smaller than the corresponding mean deviation E_{35}^{random} of 97.5% of the random time series. However, we cannot assume that each replicate simulation yields exactly six litters. We therefore repeated the above procedure four more times, but allowed additionally for random variation of the number of litters between 5–7, 4–8, 3–9, and 2–10.

Measure to compare patterns of relative bear densities. — To compare the simulated bear densities with the observed density classes, we tested how they were correlated. Because we do not know the functional relationship between the simulated bear density and the bear observation class (except that it should be a monotonic relationship) we assumed three basic cases [a quadratic (0, 1, 4, 9), a linear (0, 1, 2, 3) and a scaled square-root (0, 7, 10, 12)] relationship of the observation class to observed densities. Because our data were not necessarily normally distributed, we determined the confidence interval, separately for each of the three functional relationships, using a permutation test (Higgins *et al.*, 2000). We randomly permuted the spatial locations of the four observation classes within the given subarea and calculated the resulting correlation coefficient r . We repeated this procedure 10000 times and determined the interval that covered 97.5% of all random correlation coefficients from the left tail of the distribution. We accepted a simulated pattern to accord with the observed pattern if the correlation coefficient for at least one functional relationship was outside this 97.5% confidence interval for random permutations.

Measure for the low female density in the transition area. — In Wiegand *et al.* (*this issue*) we performed simulations with 50 times more random model parameterizations and could thus use a restrictive criterion to test for low density of resident females ($F_R < 0.008$) and dispersing females ($F_D < 0.004$) in the transition area. The best parameterizations in Wiegand *et al.* (*this issue*) yielded $F_R = 0.0074 \pm 0.0054$ females per 100 km² and year, and $F_D = 0.0038 \pm 0.0032$ females per 100 km² and year. Here we use a less restrictive criterion ($F_R < 0.012$, $F_D < 0.006$) which covers this range approximately.

WHICH TYPE OF PATTERN DATA CAN BE USED FOR MODEL CALIBRATION AND DOES CALIBRATION WITH DIFFERENT PATTERNS YIELD THE SAME MODEL PREDICTIONS?

The basic assumption of our approach to model calibration was that the data of genuine patterns filter for implausible model parameterizations, thereby restricting the model predictions obtained from the remaining model parameterizations. This assumption leads to the question of how much additional data (in the form of additional patterns) would we need to calibrate a structurally realistic spatially explicit population model for obtaining precise predictions. A second important question is whether or not model calibrations with different patterns will lead to the same model predictions, i.e., even if calibration with a given pattern yields precise model predictions (small variance), is there a bias? To answer this questions, we filter the $n = 557$ model parameterizations that do not satisfy different combinations of our five patterns (Table 4), investigate precision of the model predictions based on the remaining model parameterizations, and check the model predictions for bias.

INSERT TABLE 3

Results

SENSITIVITY ANALYSIS

As expected from the large parameter uncertainty, model predictions varied over wide ranges (Table 3). This high uncertainty in model output was also reflected in the high standard deviation of the model predictions. We found that the multiple linear regression functions were highly significant ($p < 0.0001$) for all predictions, the residuals were normally distributed, and high R^2 values ($R^2 > 0.7$) for most regressions (Table 3) indicated that the linear regression models yielded good approximations.

We found a clear sensitivity ranking (Table 3). Calculation of the average sensitivity coefficient showed that the subadult mortality rate m_{1-4} and the per step mortality rate m_s during dispersal were the most sensitive model parameters, followed by the number s^F of females leaving the core area in Slovenia, and the threshold A_{\min}^M for acceptable male home ranges. All other parameters had only moderate or low sensitivities. The parameters with the lowest sensitivity were the impact of home range size on mortality (c_m), the cub mortality rate m_0 , and the mortality rate m_{5-17} of adult bears.

IMPACT OF STOCHASTICITY ON MODEL PREDICTIONS

Our model showed demographic stochasticity caused by the low individual numbers. For five model predictions (r_{Lotka} , r_{Kalk} , $d_{\text{mean}}^{\text{M}}$, $d_{\text{mean}}^{\text{F}}$, d_{95}^{M} , md_{14}^{M}) the coefficient of variation CV ranged below 0.05 indicating a low impact of stochasticity. For seven predictions (N_{total} , R_{Kalk} , R_{Kara} , $Flux^{\text{M}}$, c_0 , c_3 , d_{95}^{F}) CV ranged between 0.05 and 0.1, for four predictions (R_{Carn} , $Flux^{\text{F}}$, r_{total} , md_{14}^{F}) it ranged between 0.1 and 0.2, and for *ext* we found $CV = 0.3$. Thus, uncertainty in model predictions due to stochasticity was roughly one order of magnitude smaller than the variation in the predictions due to parameter uncertainty (Table 3).

MEASURING THE CONCORDANCE BETWEEN OBSERVED AND SIMULATED PATTERNS

Measure to compare the pattern of females with cubs. — We found that 97.5% of all randomly created time series yielded an error index $E_{35}^{\text{random}} > 0.50$, 0.51, 0.52, 0.54, and 0.56, when varying the number of litters randomly between 6, 5–7, 4–8, 3–9, and 2–10, respectively. Wiegand *et al.* (*this issue*) based the model calibration on $> 28,000$ random model parameterizations and used the restrictive condition $E_{35}^{\text{cub}} < 0.500$ to select the parameterizations that were better than a random pattern. Here we used only data derived from 557 random model parameterizations and employed the less restrictive criterion $E_{35}^{\text{cub}} < 0.52$ to obtain a reasonable sample size. However, model predictions and their standard deviations were in general not sensitive to the selection of the threshold of E_{35}^{cub} (see also Wiegand *et al.*, *this issue*).

INSERT FIGURE 3

Measure to compare patterns of relative bear densities. — All three monotonic relationships were sufficient to capture the possible relations between observed and simulated bear densities. For example, the quadratic relationship provided the best approximation to the simulated bear density data in central Austria (Fig. 3), and yielded the highest correlation coefficient r . Our permutation test yielded 97.5% thresholds $cor = 0.25$, 0.20, 0.21 for central Austria, the Carnic Alps, and the Karawanken, respectively. The simulated bear densities were, on a 97.5% confidence level, different from a random distribution of bear observations if the correlation coefficients yields $r > cor$. The threshold cor did not differ between the three functional relationships F .

SYSTEMATIC COMPARISON BETWEEN OBSERVED AND SIMULATED PATTERNS

We found that only 12 ($\approx 2\%$) of our $n = 557$ parameterizations accorded with the observed time series of females with cubs (Table 4). By calculating the correlation coefficients between observed and simulated bear densities we found generally high correlation coefficients that were above the threshold *cor* of a random pattern. We therefore used a more restricted criterion which selected the best model parameterizations for each subarea (Table 4). The information that female densities should be low in the transition area between central and southern Austria sorted out only 9% of all model parameterizations.

INSERT TABLE 4

INSERT FIGURE 4

WHICH TYPE OF PATTERN DATA CAN BE USED FOR MODEL CALIBRATION AND DOES CALIBRATION WITH DIFFERENT PATTERNS YIELD THE SAME MODEL PREDICTIONS?

We examined how the application of different combinations of the five filters (Table 4) increases the precision of model predictions (Fig. 4). Although the application of filters 2, 3, or 4 individually filtered out some 75% of the model parameterizations, none of them reduced the high uncertainty in the model predictions as indicated by the high coefficient of variation (Fig. 4). None of them introduced a strong bias in the model predictions. In contrast, filter 5 (the time series of females with cubs) substantially reduced the variation in the model predictions (Fig. 4). However, we found that the joined application of the three filters (2+3+4) yielded basically the same estimates for model predictions as the application of filter 5 and reduced the coefficient of variation considerably (Fig. 4). Thus the key result of our analysis showed that the data for each of the three subareas taken together, restricted the model performance as well as the single “strong” filter of the time series of females with cubs. This means that the quite different data on spatial bear observations and on the temporal time series of females with cubs deliver consistent model predictions. Alternatively, we can argue that one data set provided the model calibration and the other the successful model validation. Filter 1 (low female densities in the transition area between central and southern Austria), however, provided little additional information (c.f., filter 5 with 5+1 and 2+3+4 with 2+3+4+1 in fig. 4). The result that even a relatively low number of $n = 557$ random model parameterizations of 13 model parameters yielded estimates of model predictions that did not differ from the estimates with 50 times greater simulation effort (Fig. 4) is worth mentioning

Discussion

Our results support further enthusiasm for using spatially explicit population models in conservation biology and we contradict the pessimism articulated by some authors (e.g., Wennergren *et al.*, 1995; Ruckelshaus *et al.*, 1997; Beissinger and Westphal, 1998). Although we agree with their argument that uncertainty of model parameters and processes can cause severe problems for model reliability, we do not share their conclusion that spatially explicit population models may have little practical benefit in conservation biology. We constructed a spatially explicit population model without access to direct estimates of most demographic parameters. Following the recommendations in Beissinger and Westphal (1998), this exercise would be a waste of resources because it is “composed of many times more variables parameterized with educated guesses than with data from field measurement”. Indeed, the predictions of our uncalibrated model varied over wide ranges. However, our method for model calibration used a wide range of data, not just direct estimates of parameters. The additional data was embedded in high level patterns of population dynamics and was sufficient to reduce the high uncertainty in model predictions due to uncertainty in model parameters. However, it is important to note that we do not advocate to abolish conventional data collection for direct parameter estimation. Model construction and parameterization should be based, as much as possible, on direct data, but observed patterns can provide additional data if this is not possible.

Surprisingly, spatially explicit models are rarely calibrated in ecology and especially not in conservation biology (but see Hanski, 1994; Wiegand *et al.*, 1998; Jeltsch *et al.*, 1999; Lindenmayer *et al.*, 2000; McCarthy *et al.*, 2000) since model calibration with independent datasets is standard practice in many areas (e.g., fisheries modeling, climate modeling, hydrology). Mathematical modelers have increasingly used quantitative statistical techniques for confrontation between models and data and to make rigorous inference from biological pattern (e.g., Hilborn and Mangel, 1997; Kendall *et al.*, 1999; Turchin, 2002; Wood, 2001).

SENSITIVITY ANALYSIS

The high sensitivity of the mortality rate m_{1-4} (which includes breeding females of ages 3 and 4) is in accordance with results of a sensitivity analysis of a demographic non-spatial model for brown bears in Wiegand *et al.* (1998) and accords with results from other demographic models (e.g., Gaona *et al.*, 1998). The high sensitivity of spatially explicit population models to a parameter describing mortality during dispersal was recently pointed out by Ruckelshaus *et al.* (1997). In our model, only predictions that are directly related to the dispersal process ($Flux^M$, md_{14}^M , md_{14}^F , d_{mean}^M , d_{95}^M) show a high sensitivity to dispersal parameters. This sensitivity, however, does not translate into high variation of predictions on a higher level of

population dynamics (i.e., growth rates or population sizes). This finding contradicts frequent criticism against SEPMs and is in accordance with a recent analysis of South (1999).

The high sensitivity to the number s^F of females leaving the source (core area) in Slovenia is caused by the spatial population structure. The relatively high sensitivity to the threshold A_{\min}^M for acceptable male home ranges is partly due to the high uncertainty in this parameter and the fact that it is directly related to the carrying capacity of the landscape. At the first view, the low sensitivity indices of adult mortality rates are surprising. However, the reasons for the relatively weak impact of m_{5-17} are the fact that the mortality rate m_{1-4} already includes breeding females, the specific demographic situation of the small population after the reintroduction, and the high proportion of subadult immigrants (see Fig. 6A in Wiegand *et al.*, *this issue*).

GAINS OF PATTERN-ORIENTED MODELING

There are basically three types of epistemic uncertainty in data for population models: (1) uncertainty in the formulation of the biological processes (“structural uncertainty”), (2) uncertainty in the values of the parameters of the processes (parameter uncertainty), and (3) natural stochasticity (environmental and demographic stochasticity) (e.g., Burgman and Possingham, 2000). While natural stochasticity has to be considered, astute modeling can substantially reduce structural uncertainty and parameter uncertainty.

Because the biology of brown bears, and many other species, is well known, we could construct a structurally realistic model with relatively low structural uncertainty. However, our uncalibrated model produced high variations in model predictions due to large uncertainties in parameter values (Fig. 4) and, to a lesser extent, due to natural stochasticity. But we showed that the data embedded in different high level patterns of population dynamics (i.e., the number of females with cubs, and spatial bear observations) improved precision and consistency of the model greatly. Importantly, these patterns stem from data that are commonly (and relatively easy) collected during monitoring programs. It was reassuring that application of different patterns (i.e., filter 2+3+4, and filter 5) yielded the same model predictions. If the model structure is correct, then different high level patterns of population dynamics should be redundant because they are different manifestations of the same processes and the extra data can be used for model validation. In contrast, if model predictions differ after application of different filters then the model structure and/or the model parameterization are deficient.

Whereas it might be relatively simple to reproduce one feature of a system, the simultaneous fulfillment of several patterns describing different features of the system is by far non-trivial. A reproduction (or “explanation”) of one pattern with a model does not guarantee that the model actually identified the processes or mechanisms responsible for the

patterns in reality (Levin, 1992, Moloney, 1993, Jeltsch *et al.*, 1999). Therefore, a critical assessment of whether or not a pattern is genuine is needed (Grimm *et al.*, 1996). The quantitative data of the time series of females with cubs encapsulate data on demographics and population sizes in central Austria and on immigration to this subpopulation and is thus a genuine pattern. The filters 2–4 and their joint applications (i.e., 2+3, 3+4, or 2+4), however, are only fragmentary data on relative bear densities within restricted areas. For this reason we cannot expect them to adjust the spatiotemporal dynamics of the population model within the entire study area because they leave too many degrees of freedom uncovered. However, an important result of our analysis is that the combination of several “weaker” patterns (i.e., 2+3+4) can provide the same data as one “strong” pattern (i.e., filter 5) if they together cover the essential aspects of population dynamics. Our technique is therefore especially powerful when multiple patterns are used (see also Kendall *et al.*, 1999; Railsback and Harvey, 2002). If the model is able to reproduce multiple patterns, each getting a different feature of the system, the risk that the model or the model parameterization would be wrong is lower as when relying only on one pattern (Kendall *et al.*, 1999).

When several patterns exist that constrain the performance of the model in the same way one may ask to what extent this information may be used for further model refinement. At this point one has to be realistic about structural uncertainty and natural stochasticity, and on the uncertainty in the pattern itself (i.e., measurement error). We investigated stochasticity in our model predictions by repeating model runs with the same model parameterization and found that the standard deviation of the model predictions was typically about 10% of the mean, while the remaining uncertainty of the model predictions, after applying the filters, yielded standard deviations that were typically 20% of the mean of the model predictions (Fig. 4). Therefore we cannot improve the model performance substantially without improving the structural realism and reducing the measurement error of the patterns.

Conclusion

In the past, several authors outlined the tremendous energy that is invested in developing spatially explicit population models and they argued that this research will never produce reliable guidance for conservation unless funds and human resources are expended on producing accurate, direct field estimates of dispersal rates and dispersal survival (e.g., Wennergren *et al.*, 1995; Meir and Kareiva, 1997; Ruckelshaus *et al.*, 1997; Beissinger and Westphal, 1998). The results of our analysis, however, show that this conclusion is wrong. In many cases, such as for brown bears, however, the biology of the species is very well known and spatially explicit population models that incorporate this data (i.e., structurally realistic models) can allow for a deep analysis of the dynamic of the species and for consistent predictions, even without accurate, direct field estimates of parameters on mortality, dispersal,

and reproduction rates. The key to deal with uncertainty in spatially explicit models (and indeed in any simulation model) is how, and how much of the available data are used. In this article we demonstrated the self evident fact that we can only make reliable predictions if we have sufficient data. However, the difference to conventional approaches is that the data can be provided by one or more high level patterns of population dynamics instead of being a direct field measurement of a model parameter.

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Figure legends

Figure 1. Schematic representation of brown bear observations in the eastern Alps after Kaczensky *et al.*, (1996) and Swenson *et al.*, (2000). Females in central Austria are isolated from females in northern Slovenia and southern Austria, but males from Slovenia are able to immigrate into central Austria. The ellipses encircle detailed study areas of the simulation model in central Austria, the Carnic Alps, and the Karawanken Mountains. The bear management core area in Slovenia is shown in dark gray color.

Figure 2. The patterns. (A): The time-series of females with cubs of the year (COY) in central Austria. Note that zero values indicate no observation, but not no data. (B): Data on bear observations classes from 1989–1999 transformed to the 10 km × 10 km grid of the habitat model. White: no data, light gray: no observation, intermediate gray: sporadic observations (1–3), dark gray: regular observations (4–10), black: many observations (>10). The black rectangle in the transition area between central and southern Austria encircles an area where no female bears were observed.

Figure 3. Calculation of the correlation coefficients r to measure the deviance between the observed bear densities and the simulated bear densities [bears / (100km² yr)], shown for one model parameterization and the area of central Austria. (A) Quadratic relationship of the observation class to observed densities, (B) linear relationship, and (C) scaled square-root relationship. The observation classes are: no observation (class 0), 1–3 observations (class 1), 4–10 observations (class 2), and > 10 observations (class 4). Boxes summarize median and

the inner 50%, whiskers the inner 80% of the simulated data, and points show the data outside the inner 80% of the data.

Figure 4. Application of the 5 filters (Table 4) alone and in combination and restriction of model predictions. The gray bars give the mean value of the prediction based on the n model parameterizations that passed the filters 1–5 and their combinations (x-axis). The error bars give the standard deviation, and the black bars show the coefficient of variation (SD/mean). The horizontal lines give the estimate of the predictions from Wiegand *et al.* (*this issue*) (solid horizontal) and the envelopes of the standard deviations (dashed horizontals) which were based on 50 times more random model parameterizations and a more restricted filter criterion.

Tables

Table 1. The 13 model parameters and their ranges. J : hunting mortality in Slovenia before 1992, s^F , s^M : mean number of females and males leaving the core area per year, a : parameter describing home range overlap, A^F_{\min} and A^M_{\min} : attractiveness threshold for acceptance of female and male home ranges, S^F_{\max} and S^M_{\max} : maximum number of site sampling steps per year for females and males, c_m : impact of home range size on mortality, m_i : annual mortality rate at age i , m_s : per step risk of mortality during dispersal.

Parameter	J	s^F	s^M	A	A^F_{\min}	A^M_{\min}	S^F_{\max}	S^M_{\max}	c_m	m_0	m_{1-4}	m_{5-17}	m_s
Range min	0.04	0.0	0	0.1	49	50	5	10	0	0.2	0.08	0.08	0.001
Range max	0.70	0.7	3	0.5	58	65	40	50	1	0.5	0.28	0.18	0.008

Table 2. Model predictions investigated.

Symbol	Meaning
Residents	
N_{total}	Total population size in Austria and adjacent parts of Italy in 2000.
R_{Kalk}	Total number of residents in central Austria (see Fig. 2) in 2000.
R_{Carn}	Total number of residents in the Carnic Alps (see Fig. 2) in 2000.
R_{Kara}	Total number of residents in the Karawanken (see Fig. 2) in 2000.
Mean flux	
$Flux^{\text{M}}$	Net annual flux of males from Austria to Slovenia (immigrants - emmigrants)
$Flux^{\text{F}}$	Net annual flux of females from Austria to Slovenia (immigrants - emmigrants)
Growth rates	
r_{Lotka}	For Austria and adjacent parts of Italy, using mortality and reproduction events
r_{total}	For Austria and adjacent parts of Italy, using the 1995 -2000 population numbers
r_{Kalk}	Growth rate for central Austria using the 1995 -2000 numbers of residents
ext	Number of extinct replicate simulations
Reproduction	
c_0	Mean number of cubs expected by a female cub
c_3	Mean number of cubs expected by a subadult female of 3 years
Dispersal	
$d_{\text{mean}}^{\text{M}}$	Mean dispersal distance [in 10 km] (mother home range to own home range) for males
$d_{\text{mean}}^{\text{F}}$	Mean dispersal distance [in 10 km] (mother home range to own home range) for females
d_{95}^{M}	95% percentile [in 10 km] of male dispersal distances
d_{95}^{F}	95% percentile [in 10 km] of female dispersal distances
md_{14}^{M}	Mean dispersal mortality for males in age class 1 - 4 years
md_{14}^{F}	Mean dispersal mortality for females in age class 1 - 4 years

Table 3. Sensitivity analysis of model predictions based on $n = 557$ random model parameterizations. Given are the mean \pm the standard deviation, the minimum and the maximum value of the model prediction, the R^2 of the multiple linear regression with the prediction as dependent variable and the 13 model parameters as independent variables, and the resulting sensitivity coefficient S for each model parameter. For symbols of model parameters and model predictions see Tables 1 and 2.

Prediction	Mean \pm SD	Min	Max	R^2	Sensitivity coefficient $S (= \beta_i)$ for model parameters i												
					J	s^F	s^M	a	A_{\min}^F	A_{\min}^M	S_{\max}^F	S_{\max}^M	c_m	m_0	m_{1-4}	m_{5-17}	$1/m_s$
N_{total}	15.6 \pm 13.4	1.7	92.9	0.69	-0.12	0.19	0.09	0.00	-0.01	-0.14	0.01	-0.04	0.00	-0.03	-0.23	-0.04	0.24
R_{Kalk}	4.25 \pm 2.08	1.37	17.11	0.76	-0.04	0.06	0.06	-0.09	-0.03	-0.21	0.04	-0.02	-0.02	-0.05	-0.23	-0.04	0.19
R_{Carn}	1.96 \pm 1.60	0.06	11.06	0.75	-0.10	0.24	0.10	-0.05	-0.08	-0.17	0.06	-0.01	-0.01	-0.03	-0.20	-0.06	0.07
R_{Kara}	4.02 \pm 2.84	0.06	20.51	0.75	-0.09	0.22	0.10	-0.12	-0.07	-0.15	0.05	-0.02	-0.01	-0.02	-0.17	-0.05	0.05
$Flux^M$	0.61 \pm 0.59	-0.01	3.11	0.71	-0.10	0.19	0.28	-0.02	-0.04	-0.08	0.01	-0.14	0.00	-0.03	-0.10	-0.02	0.46
$Flux^F$	0.22 \pm 0.23	-0.01	1.39	0.71	-0.18	0.32	0.10	0.03	0.01	-0.07	0.05	0.00	0.00	-0.05	-0.22	-0.05	0.13

Table 3 continued

r_{loka}	-0.019 ± 0.087	-0.661	0.218	0.77	-0.03	0.06	0.03	-0.02	0.00	-0.15	-0.01	-0.04	0.00	-0.01	-0.21	-0.01	0.13
r_{total}	0.087 ± 0.061	-0.098	0.249	0.74	-0.03	0.21	0.02	-0.05	0.00	-0.18	0.01	-0.06	-0.03	-0.06	-0.38	-0.08	0.14
r_{Kalk}	0.017 ± 0.043	-0.114	0.157	0.71	-0.04	0.08	0.03	-0.07	0.02	-0.24	0.04	-0.07	-0.02	-0.06	-0.30	-0.10	0.19
ext	28.6 ± 17.7	1.0	99.0	0.75	0.04	-0.03	0.01	0.05	0.02	0.06	-0.03	0.02	0.11	0.15	0.48	0.12	-0.10
md_{14}^M	0.39 ± 0.22	0.04	0.94	0.80	-0.04	0.02	0.16	0.05	-0.01	0.31	-0.06	0.39	-0.01	0.00	-0.03	-0.02	-0.70
md_{14}^F	0.032 ± 0.024	0.000	0.147	0.65	-0.11	0.19	0.06	0.14	0.11	-0.09	0.19	-0.02	-0.03	-0.04	-0.15	-0.06	-0.32
d_{mean}^M	9.7 ± 2.4	4.4	14.7	0.53	-0.04	0.08	0.32	0.05	-0.04	0.05	0.02	-0.11	-0.03	0.00	-0.07	-0.05	0.59
d_{mean}^F	3.4 ± 1.1	1.0	6.7	0.83	-0.14	0.34	0.10	0.26	0.19	-0.10	0.20	0.00	-0.02	-0.03	-0.23	-0.06	0.14
d_{95}^M	20.9 ± 4.0	7.0	27.0	0.45	0.01	-0.02	0.24	0.03	-0.02	0.05	0.02	-0.14	-0.04	-0.01	-0.04	-0.03	0.46
d_{95}^F	8.3 ± 2.7	2.0	16.0	0.78	-0.13	0.34	0.10	0.17	0.19	-0.08	0.24	0.01	-0.03	0.00	-0.19	-0.05	0.12
c_0	0.98 ± 0.40	0.04	3.09	0.78	-0.05	0.08	0.04	-0.02	-0.01	-0.18	-0.01	-0.03	-0.01	0.00	-0.29	-0.03	0.18
c_3	1.83 ± 0.63	0.14	4.33	0.79	-0.10	0.16	0.08	0.00	0.01	-0.26	0.03	-0.05	-0.01	-0.02	-0.24	-0.05	0.19
Average sensitivity coefficient of model parameters																	
		0.08	0.16	0.11	0.07	0.05	0.14	0.06	0.06	0.02	0.03	0.02	0.03	0.02	0.21	0.05	0.24

Table 4. Filters defined through observed patterns. F_D , F_R : mean simulated density of dispersing and resident females, respectively, within the box shown in Fig. 3B; r : correlation between bear observation class and simulated bear density; E_{35}^{cub} error index between observed and simulated time series of females with cubs.

Filter description	Filters	Condition	Number of model parameterizations in accordance with observed pattern
No filter	0	-	557
Density of females in transition area	1	$F_D < 0.006$ $F_R < 0.012$	506
Bear observations in central Austria	2	$r > 0.72$	138
Bear observations in the Carnic Alps	3	$r > 0.62$	154
Bear observations in the Karawanken	4	$r > 0.63$	180
Females with cubs	5	$E_{35}^{\text{cub}} < 0.52$	12
	2 + 3		63
	2 + 4		33
	3 + 4		50
	2 + 3 + 4		13
	5 + 1		10
	2+3+4+1		11

Figures

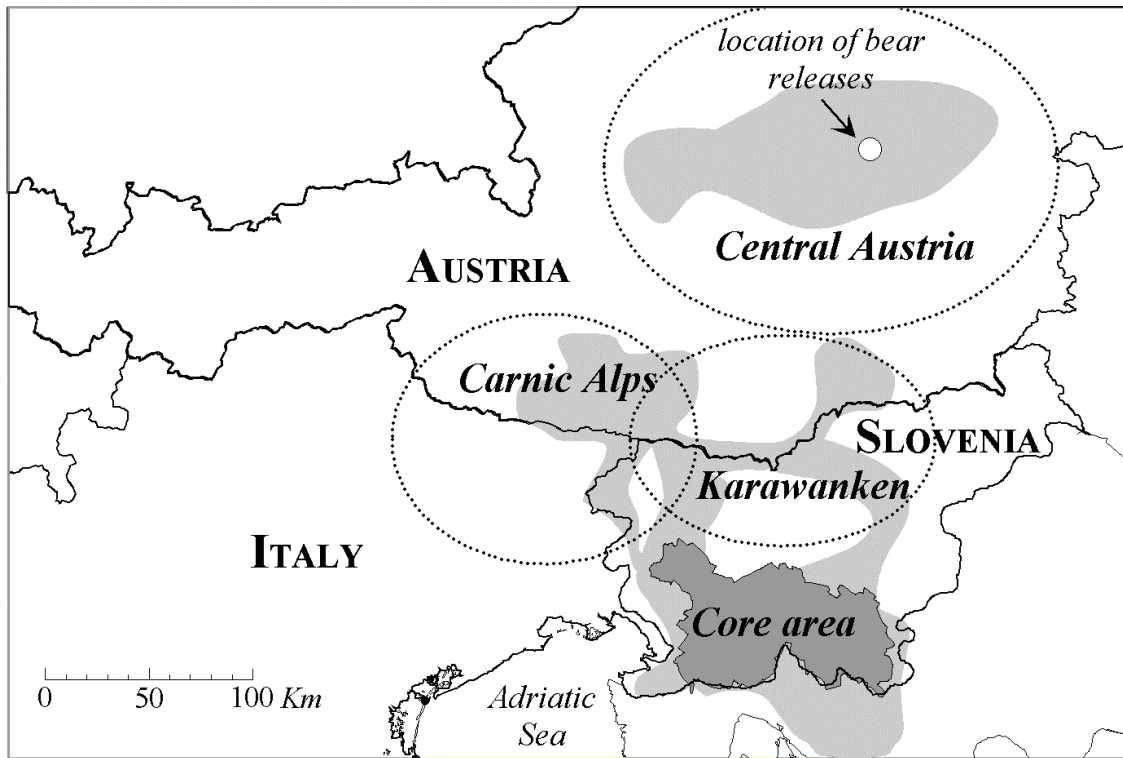


Figure 1

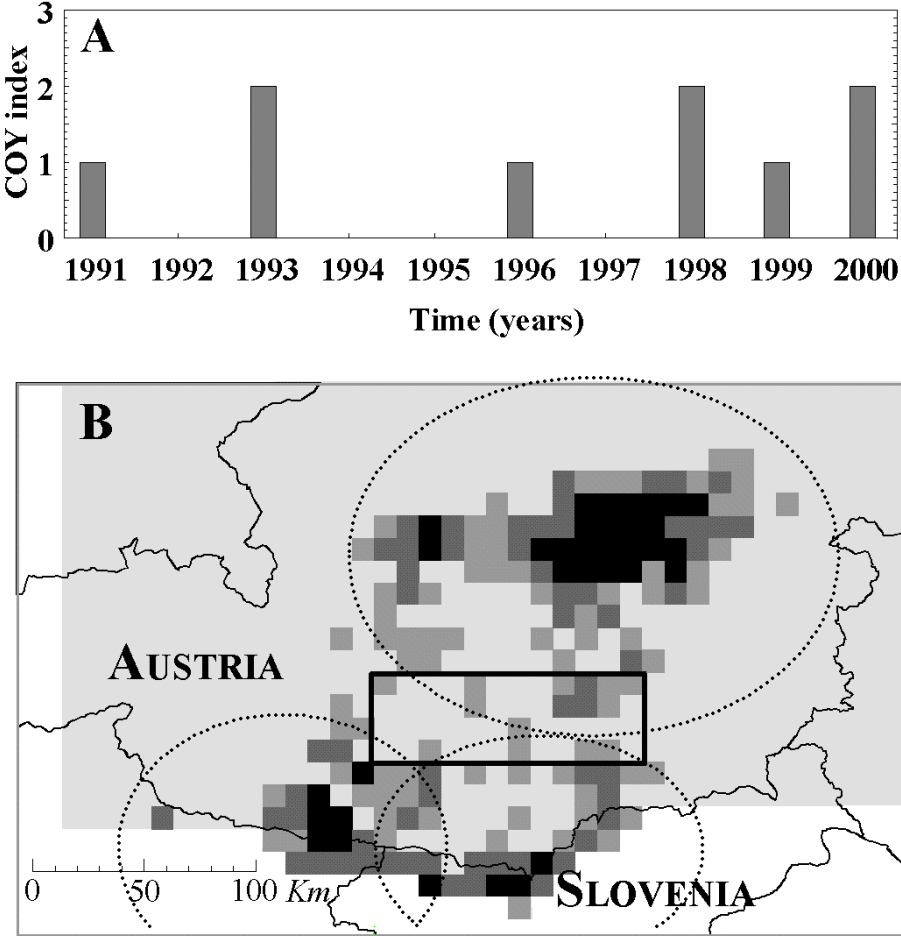


Figure 2

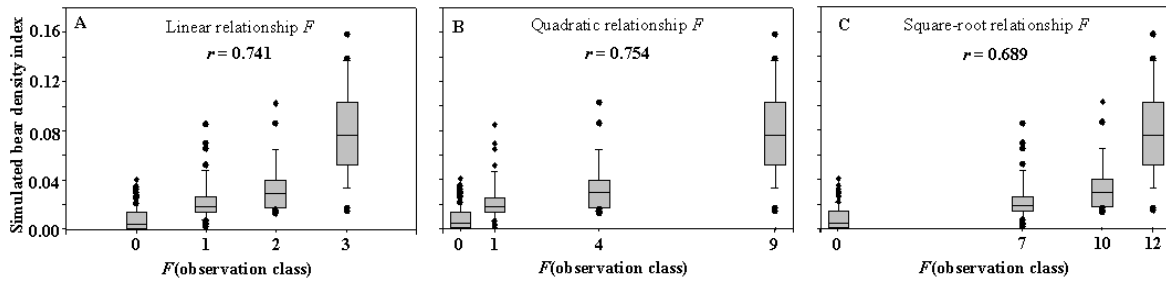


Figure 3

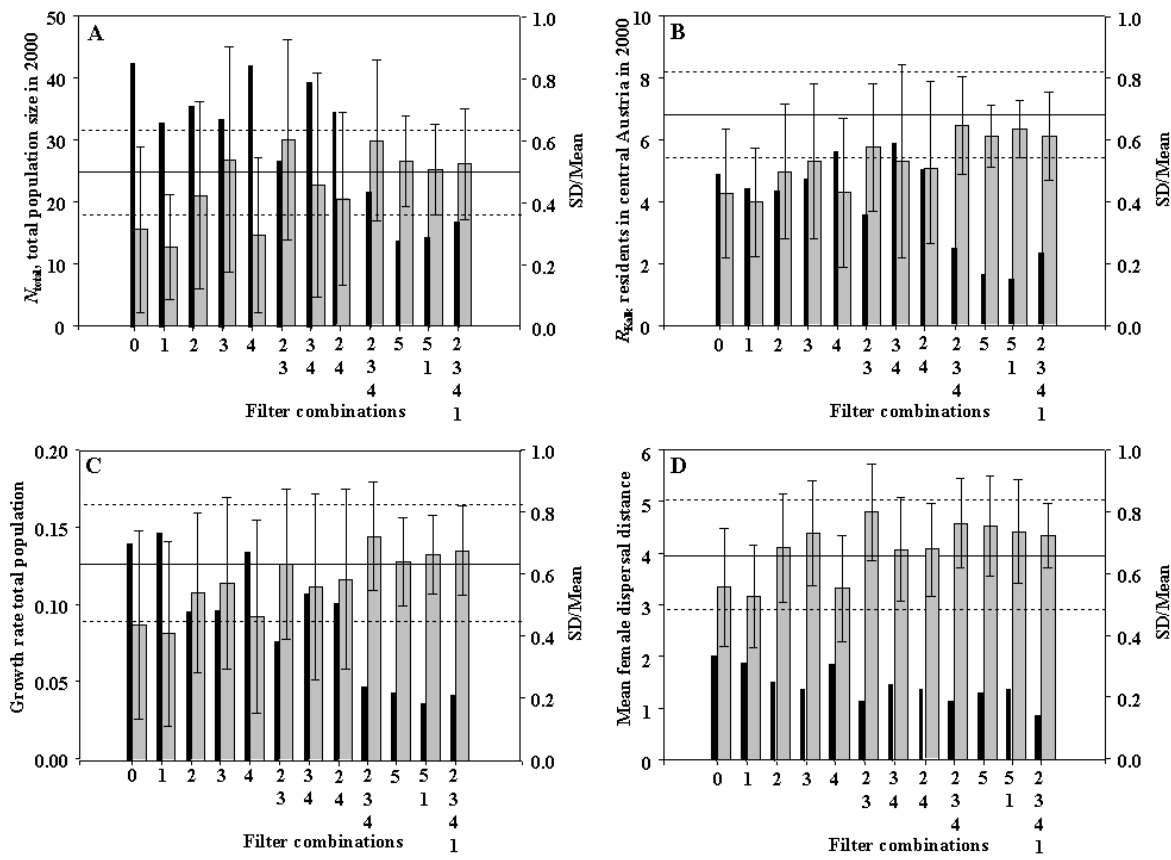


Figure 4